Netzer Precision Motion Sensors Ltd.

DF-150-32

Absolute position, rotary Electric Encoder™

The DF-150 is a member of the DF series of Electric Encoder[™], based on Netzer Precision proprietary technology. The Electric Encoder[™] offers many advantages - some unparalleled The Electric Encoder[™] offers many technology. The Electric Encoder[™] offers many advantages - some unparalleled The Electric Encoder[™] offers many forgiving to mounting tolerances, mechanical wander etc.

Low profile (13 mm). Hollow, floating shaft. No bearings or other contacting elements. High resolution and precision. High tolerance to temperature extremes , shock, moisture, EMI, RFI and Magnetic fields. Very low weight. Holistic signal generation Digital interfaces.

Mechanical	
Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	215,847 gr · mm ²
Total weight	310 gr
Outer Ø /Inner Ø/ Height	150/ 110 / 13 mm
Material (stator, rotor)	Aluminum
Nominal air gap (stator, rotor)	0.6 mm

Electrical		
Supply voltage	5V ± 5%	
Interconnection	Shielded cable or	
Cable Length	1,500 mm MAX	
Environmental		
EMC	IEC 6100-6-2, IEC 6100-6-4	
Operating temperature range	Digital: -40°C to +85°C	
Relative humidity	98% Non condensing	
Shock endurance	100 g for 11 ms	
Vibration endurance	20 g 10 – 2000 Hz	
Protection	IP 40	

Characteristics	
Angular resolution	18 bits ; 262,144 CPR
Static error	< 10 mDeg
Maximum operational speed	750 rpm
Measurement range	Unlimited rotation
Build In Test BIT	Optional

The Electric Encoder[™] is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder[™] forgiving to mounting tolerances, mechanical wander etc. The absence of components such as ball bearings, flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder[™] virtually failure free.

The internally shielded, DC operated Electric Encoder[™] includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric EncoderTM are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.





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SYNCHRONOUS SERIAL INTERFACE

Digital SSi Interface

Synchronous Serial Interface (**SSI)** is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12-22
Т	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	



SSi / BiSS Output signal parameters		
Signal latency	~250 µSec	
Output code	Binary	
Serial output	Differential RS-422	
Clock	Differential RS-422	
Clock Frequency	0.5 ÷ 2.0 MHz	
Position update rate (Max)	30 KHz	
Current consumption	180 mA	

SSi	
Monoflop time	25 μSec

SSi / BiSS interface wires color code				
Clock +	Grey	Clock		
Clock -	Blue	LIUCK		
Data -	Yellow	Data		
Data +	Green	Dala		
GND	Black	Ground		
+5V	Red	Power supply		

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied **Electric Encoder Explorer** software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



BISS Interface /

Digital BiSS-C Interface

BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.



bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"O"	"start" bit follower	0	1 bit
825	AP	Absolute Position encoder data		
7	Warn.	Warning	1	1 bit
6	Error	Error	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 µs



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DF - 150 - 32 - 5 G	- 5 0 - n n n
DF Product line	nnn - Custom
Outer Diameter	C - Connector (optional) O - Flying leads (default)
Fine ECR	Interconnection:
Outputs:	S - shielded cable 250 mm (default)
S - Digital : SSi I - Digital : BiSS-C	
Resolution	
Code Bit CPR G 18 262,144	
BIT (Build In Test): optional	
[] - none B - BIT	

Netzer Cat No.: CB-00014	Pair #	Color	
Provider: Ray-Q USA. wire CAT No: RQ213210 Cable: 30 AWG twisted pair (3) :2 (30 AWG 25/44 finned copper, 0.15 PFE to Ø0.6 ± 0.05 OD). Temperature rating: -60 to +150 Deg C.		Red / Black	
		Gray / Blue	
		Green / Yellow	
Braided shield: Thinned copper braided 95% min. coverage.			
Jacket: 0.45 silicon rubber jacket Ø3.45 ±0.2 OD			
30 AWG twisted pairs (3) 0.017- Braided shield Jacket 0.45mm		30 AWG si insulated	0
3.45 ± 0.20mm			

Ø 0.61 ± 0.051mm



DF-150 User Manual : Mechanical , Electrical and calibration

Demonstration Kit:

 $\mbox{DF-150DKIT-01:}\ \mbox{Includes}\ \mbox{,mounted encoder}\ \mbox{on rotary}\ \mbox{jig}\ \mbox{, and}\ \mbox{RS-422}\ \mbox{to}\ \mbox{USB}\ \mbox{converter}.$

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