Absolute Position
Rotary Electric Encoder™ | VLX-60 Qcore

The VLX-60 is a member of the VLX series of Electric Encoders™ a product line based on Netzer Precision Motion Sensor proprietary technology. EE products are characterized by features that enable unparalleled performance:

- Low profile (<10 mm)
- Hollow shaft (Stator / Rotor)
- No bearings or other contact elements
- High resolution and unparalleled precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and magnetic fields
- Very low weight
- Holistic signal generation
- Digital interfaces for absolute position

The holistic structure of the Electric Encoder™ makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.

Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.

The internally shielded, DC- operated EE includes an electric field generator, a field receiver, sinusoidal–shaped dielectric rotor, and processing electronics.

The EE output is a digital serial synchronous with absolute position single turn.

This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation applications.

General

Angular resolution [1]	18 bits ; 262,144 CPR
Static error	< 0.015°
Maximum operational speed	4,000 rpm
Measurement range	Single turn, unlimited

Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	8,669 gr · mm^2
Total weight	28 gr
Outer Ø /Inner Ø/ Height	60 / 25/ 10 mm
Material (stator, rotor)	FR4
Nominal air gap (stator, rotor)	0.6 mm

Electrical

Supply voltage	5V ± 5%
Current consumption	<70 mA
Interconnection	Connector

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature	-20°C to +65°C
Storage temperature	-40°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40

Calibration / Compensation

Offsets	Automatic / Manual
Signals level	Automatic / Manual
Signals integrity	Error / Warning report
Thermal	Error / Warning report
Zero position	Manual

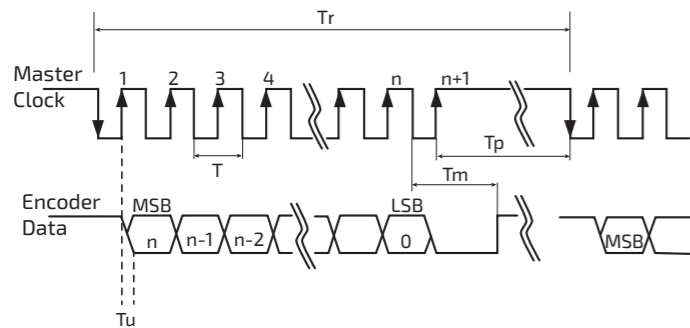● *Moving. Precisely. With You.*

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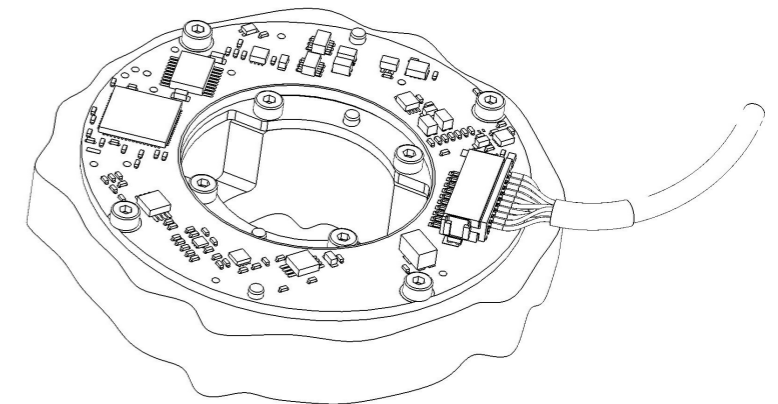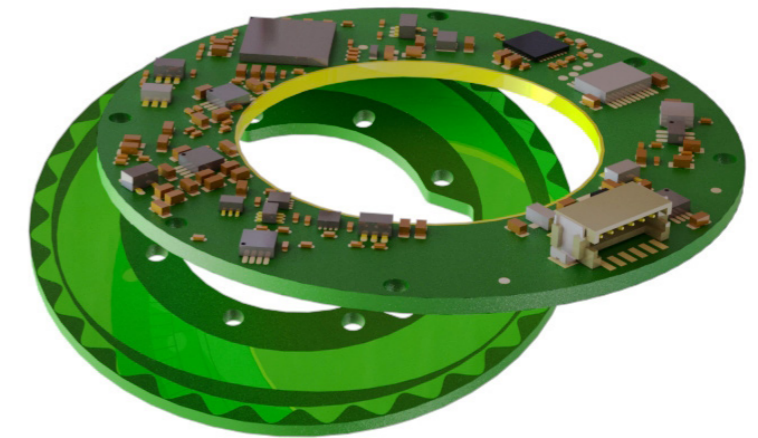
Digital SSi Interface

Synchronous Serial Interface (SSI) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.


Description		Recommendations
n	Total number of data bits	12 - 22
T	Clock period	
f= 1/T	Clock frequency	0.1 - 5.0 MHz
Tu	Bit update time	90 nsec
Tp	Pause time	26 - ∞ μsec
Tm	Monoflop time	>25 μsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 μsec
fr=1/Tr	Data request frequency	

SSi / BiSS output signal parameters

Signal latency	50 μSec
Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.1 ÷ 5.0 MHz
Position update rate	30 KHz

SSi / BiSS interface wires color code

| Clock +	Grey	Clock
Clock -	Blue	
Data -	Yellow	Data
Data +	Green	
GND	Black	Ground
+5V	Red	Power supply

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied Electric Encoder Explorer software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.
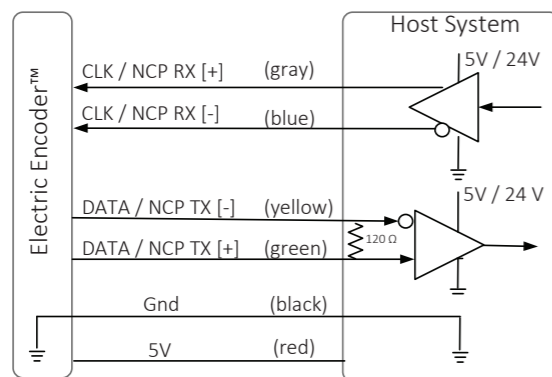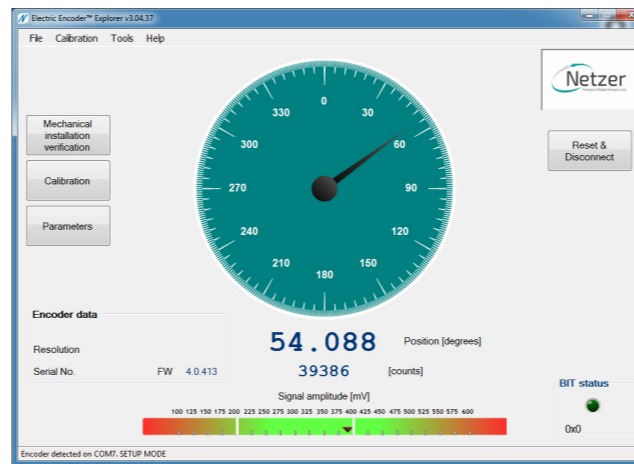
Digital BiSS-C Interface

BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.
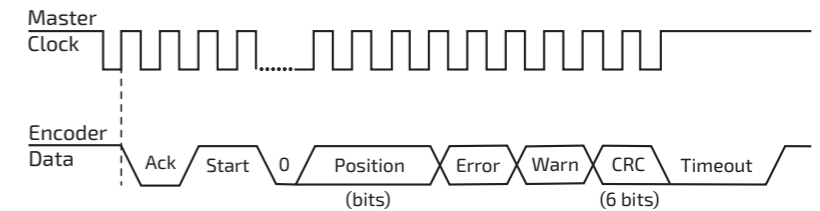
Bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"0"	"start" bit follower	0	1 bit
8...25	AP	Absolute Position encoder data		
7	Error	Error (BIT Optional)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
0...5	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 μs

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Ordering Code

VLX - 60 - S H - C H

VLX Product line

Outer Diameter

Output

S	SSi
I	BiSS

Resolution

Code	Bit	CPR
G	18	262,144
H	19 [1]	524,288

Notes

[1]	Resolution - optional, call

Interconnection

H	Connector - Horizontal
V	Connector - Vertical
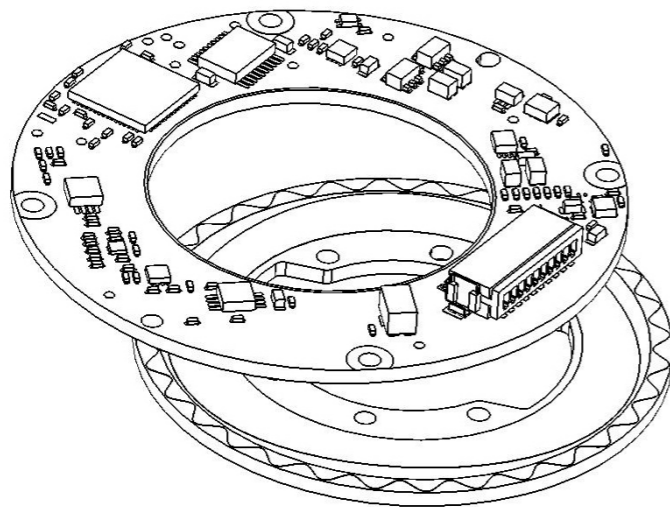
Optional Accessories

Interconection - connector HRS DF13-10S-1.25

#	SSi / BiSS	Remarks
8	5V	P.S.
7	GND	GND /RTN
6	Data+	Data / NCP TX
5	Data-	Data / NCP TX
4	Clock-	Clock / NCP RX
3	Clock+	Clock / NCP RX

1 -
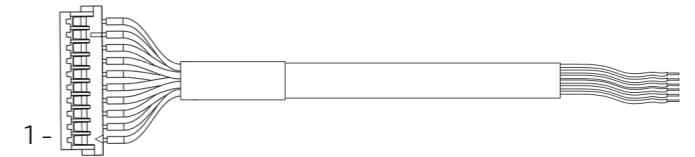
Accessories - cables, optional

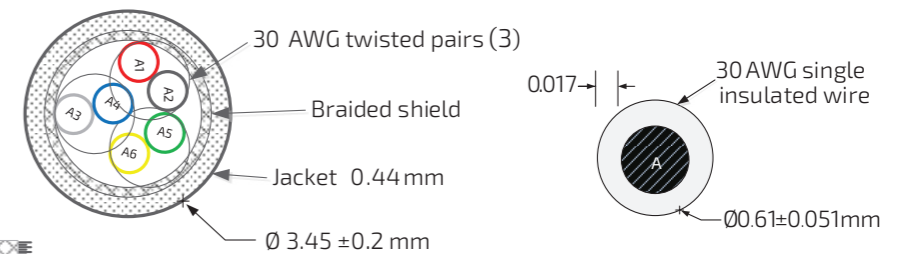| SSi / BiSS	Remarks
CB-00088-250	AWG30, 250 mm
CB-00088-500	AWG30, 500 mm

Netzer Cat No.: CB 00014
Provider: Ray-Q USA. CAT No.: RQ 213210
Cable: 30 AWG twisted pair (3): 2 (30 AWG 25/44 tinned copper,
Insulation: PFE Ø 0.15 to Ø 0.6 ± 0.05 OD).
Temperature rating: -60 to +150 Deg C.
Braided shield: Thinned copper braided 95% min. coverage.
Jacket: 0.44 silicon rubber (NFA 11-A1) Ø3.45 ±0.2 OD

Pair #	Color
A1-A2	Red / Black
A3-A4	Gray / Blue
A5-A6	Green / Yellow

30 AWG twisted pairs (3)

Braided shield

Jacket 0.44 mm

Ø 3.45 ±0.2 mm

0.017

30 AWG single insulated wire

Ø0.61±0.051mm

Related documents

LX-60 User Manual : Mechanical , Electrical and calibration setup.

Demonstration Kit
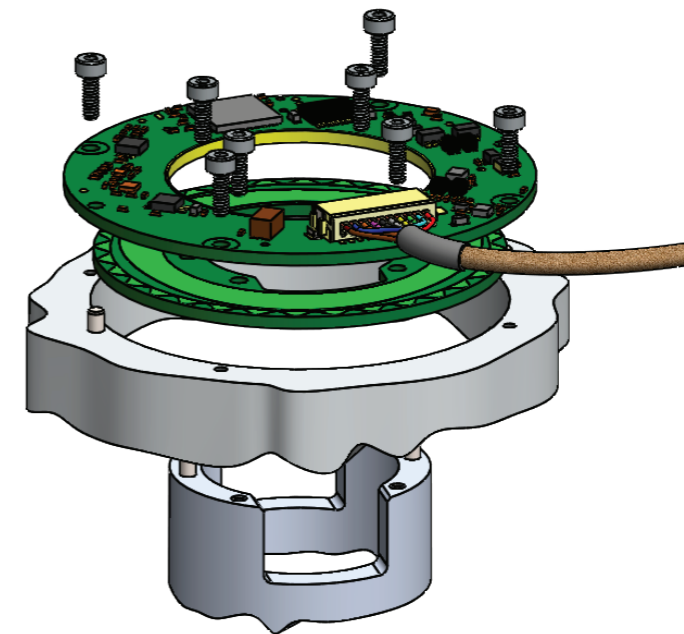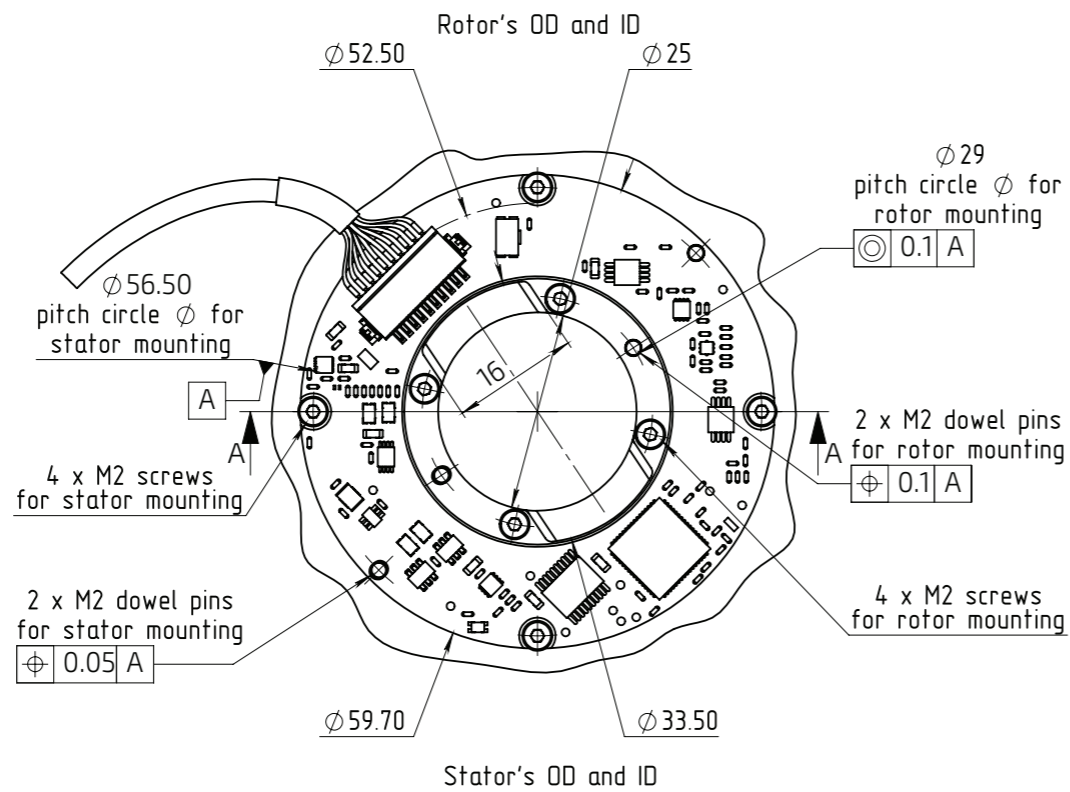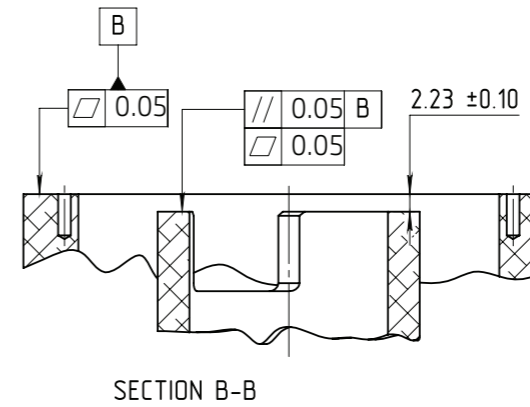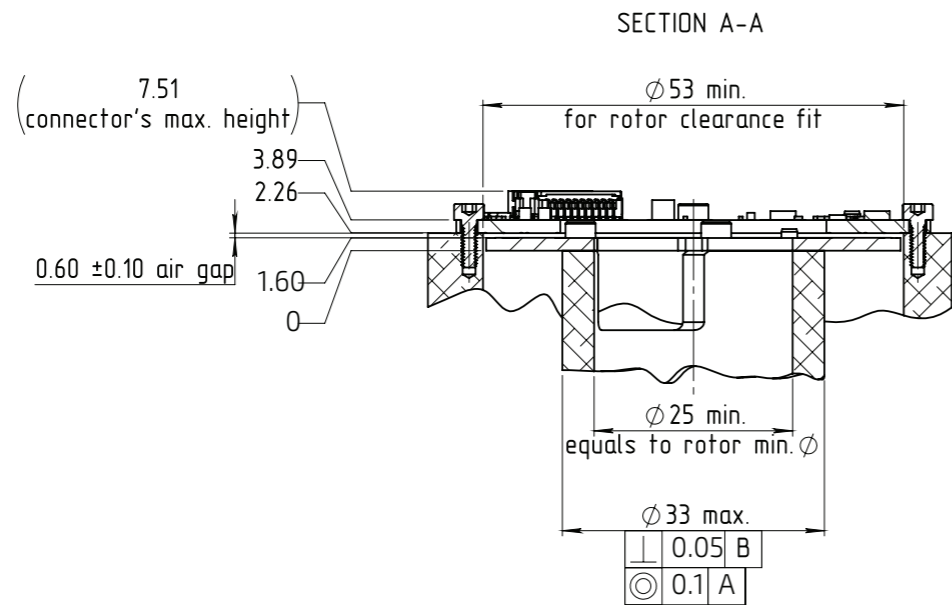
DKIT-VLX-60-SG with SSi interface
DKIT-VLX-60-IG   withe BiSS interface
Includes, mounted encoder on rotary jig,
and RS-422 to USB converter.

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SECTION A-A

7.51 (connector's max. height)

3.89
2.26
0.60 ±0.10 air gap
1.60
0

$\emptyset$ 53 min. for rotor clearance fit

$\emptyset$ 25 min. equals to rotor min. $\emptyset$

$\emptyset$ 33 max.

| ⊥ | 0.05 | B |
| ◎ | 0.1 | A |

SECTION B-B

B

| ▱ | 0.05 |

| ∥ | 0.05 | B |
| ▱ | 0.05 |

2.23 ±0.10

Rotor's OD and ID

$\emptyset$ 52.50
$\emptyset$ 25

$\emptyset$ 29 pitch circle $\emptyset$ for rotor mounting
| ◎ | 0.1 | A |

$\emptyset$ 56.50 pitch circle $\emptyset$ for stator mounting

A

16

2 x M2 dowel pins for rotor mounting
| ⊕ | 0.1 | A |

4 x M2 screws for stator mounting

2 x M2 dowel pins for stator mounting
| ⊕ | 0.05 | A |

4 x M2 screws for rotor mounting

$\emptyset$ 59.70
$\emptyset$ 33.50

Stator's OD and ID

UNLESS OTHERWISE SPECIFIED

Dimentions are in: mm
Surface Finish: N6
Linear Tolerances: ±0.5 deg
All Chamfer: 0.1 mm x 45°

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