



The DS-37 is a member of the DS series of Electric Encoders[™], based on Netzer Precision proprietary technology. The Electric Encoder[™] offers many advantages - some unparalleled

- Low profile (8 mm)
- Hollow, floating shaft
- No bearings or other contacting elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Very low weight
- Holistic signal generation
- Analog or Digital interfaces

General

Angular resolution	17-19 bit		
Maximum tested static error	≤ 0.025°		
Extended accuracy static error	≤ 0.015°		
Maximum operational speed	1,500 rpm		
Measurement range	Unlimited rotation		
Power On - Max. operational speed	3.3 RPM, <=20°/sec		
Rotation direction	Adjustable CW/CCW*		
Build In Test BIT	Optional		
* Default same direction from bottom side of the encoder			

Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	70.93 gr · mm²
Total weight	10 gr
Outer Ø /Inner Ø/ Height	37 / 10 / 8 mm
Material (stator, rotor)	Ultem™ polymer / TRVX-50

The Electric EncoderTM is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric EncoderTM forgiving to mounting tolerances, mechanical wander etc.

The absence of components such as ball bearings, flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder[™] virtually failure free.

The internally shielded, DC operated Electric Encoder[™] includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder[™] are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.

Electrical

Supply voltage	5V ± 5%
Interconnection	Shielded cable
Cable Length	1,500 mm MAX

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature range	-40°C to +85°C
Storage temperature	-50°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40











Digital SSi Interface

Synchronous Serial Interface **(SSI)** is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 22
Т	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Тр	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	



SSi / BiSS Output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.5 ÷ 2.0 MHz
Position update rate (Max)	30 KHz
Current consumption	180 mA

SSi / BiSS interface wires color code

Trov	
леу	Clock
Blue	Clock
/ellow	Data
ūreen	Dala
Black	Ground
Red	Power supply
	rey lue ellow reen lack ed

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied <u>Electric Encoder Explorer software</u>, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



BISS

HARSH

ENVIRONMENT

Digital BiSS-C Interface

DATA SHEET

DS-37

BiSS – **C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

Master Clock



bit #		Description Defau		Length
27	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
26	Start	Encoder signal for "start" data transmit	1	1 bit
25	"0"	"start" bit follower	0	1 bit
824	AP	Absolute Position encoder data		
7	Error	Error (amplitude levels)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x6 + x1 + x0$. It is transmitted MSB first and inverted.		6 bits
		The start bit and "0" bit are omitted from the CRC calculation.		
	Timeout	Fineout Elapse between the sequential "start"request cycle's.		25 µs

DS-37-V02





Analog Interface

Coarse and Fine channels

The DS-37 has two operational modes: a Coarse-mode and a Fine-mode - equivalent to two separate encoders in a common housing. The modes are selectable by a logic C/F command; logic "0" (OV to +0.5V) selects the Coarse-mode, which has 3 Electrical Cycle/Revolution (EC/R) while logic "1" (+3V to +5V) selects the Fine-mode which has 16 EC/R.

The switching time is less than 1 ms.

The Coarse-mode outputs need to be read only upon system initiation after which the encoder is permanently switched to the Fine mode. Coarse and Fine sine / cosine pairs are used to calculate the initial absolute position, from that point tracking the Fine-channel outputs provides the absolute mechanical rotation angle with the specified accuracy and resolution.

All output signals are referenced to an internally generated voltage Vr (~2.25V) $\,$



Output Signal Parameters

Electric Cycles (Fine / Coarse channels)	16 / 3
Signal latency	250 µSec
Fine-mode output noise (DC to 1kHz)	100 µV (р-р)
Fine-mode output amplitude	±400mV ± 20%
Coarse-mode output amplitude	±300mV ± 20%
Phase relationship	Cipo loade Cocipo
(CW shaft rotation - seen from top)	Sille teaus cosille
Signal bandwidth	DC to 1 kHz
Current consumption	10mA



Analog interface wires color code

1	GND	Black	Ground
2	C/F	Grey	Coarse / Fine
3	Sine	Blue	Sine signal
4	Vr	Green	V referenceCosine signal
5	Cosine	Yellow	Cosine signal
6	+5V	Red	P.S.

Absolute Position calculation

The analog Sine / Cosine outputs convey the Electrical angle of the Coarse or Fine signals. The Absolute mechanical angle is computed by digitizing the analog signals.



DS-37-V02











Unless otherwise specified DS-37-V02 Dimensions are in: mm Surface finish: N6 Linear tolerances: ±0.1 deg

Adhesive EC-2216 B/A.





DATA SHEET



DS-37-V02









Unless otherwise specified Dimensions are in: mm Surface finish: N6 Linear tolerances: ±0.1 deg

DS-37-V02

SC2SSi, DS-37 external digital module (SSi/BiSS)

No	No Part		Description	QTY.	
1	SC2SSi-03	Included		with DS-37 CAT No.	1